Avian Influenza Vaccination of Poultry and Passive Case Reporting, Egypt

Timothée Vergne, Vladimir Grosbois, Yilma Jobre, Ahmed Saad, Amira Abd El Nabi, Shereen Galal, Mohamed Kalifa, Soheir Abd El Kader, Gwenaëlle Dauphin, François Roger, Juan Lubroth, and Marisa Peyre

We investigated the influence of a mass poultry vaccination campaign on passive surveillance of highly pathogenic avian influenza subtype (H5N1) outbreaks among poultry in Egypt. Passive reporting dropped during the campaign, although probability of infection remained unchanged. Future poultry vaccination campaigns should consider this negative impact on reporting for adapting surveillance strategies.

Egypt reported its first occurrence of highly pathogenic avian influenza (HPAI) virus subtype H5N1 in poultry on February 16, 2006 (1), and its first case in a human on March 20, 2006. As of June 2011, Egypt was the country most affected by HPAI (H5N1) outside of Asia (2). Vaccination of domestic (backyard) and commercial poultry, which began in March 2006, and other measures were implemented to control the disease, but outbreaks among poultry and humans continued to be regularly reported from various districts located mainly in the delta region of the country (3). In July 2009, vaccination of domestic poultry was stopped (4). The objective of this study was to assess the effect of vaccination of domestic poultry on the passive reporting of HPAI (H5N1) cases among poultry. The completeness of the passive surveillance of poultry cases at the district level during and after the mass vaccination campaign was estimated by using a 4-source capture-recapture method (5).

The Study

Two periods were selected for study: period 1 (December 2008–June 2009), during which mass vaccination of backyard poultry was ongoing, and period 2 (December 2009–June 2010), during which mass vaccination had ceased (Figure). Vaccination of commercial poultry in Egypt against avian influenza (AI) continued throughout the study period. In Egypt, the district level is the smallest administrative unit used for defining surveillance and control strategies related to HPAI (H5N1) among poultry. Thus, we used the district level to estimate the occurrence of HPAI (H5N1) during the 2 study periods.

HPAI (H5N1) circulation in poultry is recorded by the national surveillance of poultry coordinated by the General Organization for Veterinary Services (GOVS) in conjunction with the Central Laboratory for Quality Control of Poultry Production, based in Cairo. During the 2 study periods, poultry surveillance was structured into 3 distinct protocols: 1) passive surveillance reliant on disease reporting by farmers; 2) active surveillance of preslaughter poultry and high-risk areas (areas defined by GOVS as high risk based on specific criteria, such as the density of the poultry population and the detection of HPAI (H5N1) cases among humans and poultry in previous months); and 3) the community based animal health outreach program, a participatory surveillance network that relies on traditional information networks to track down and confirm HPAI (H5N1) events in areas where virus circulation is suspected.

The lists of cases collected through these complementary protocols by GOVS and the Central Laboratory for Quality Control of Poultry Production was provided by the Emergency Centre for Transboundary Animal Diseases Unit of the Food and Agriculture Organization in Egypt. Since 2006, the government has required the culling of poultry flocks in which cases of avian influenza were detected. As part of the initial program, government compensation for culled birds was also implemented, but because of misuse, the compensation program was stopped in 2007.

It is assumed that most human cases of influenza (H5N1) are linked to infections in poultry (3,6,7); thus, we postulated that a human case within a district revealed avian influenza (H5N1) virus circulation among poultry within that district. For methodological purposes, we hypothesized that a human could not get the infection from outside the district of residence. In Egypt, the protocol for surveillance of human influenza cases is based on reporting of suspected cases in district hospitals followed by confirmation of infection by the Central Public Health Laboratory in Cairo and the US Naval Medical Research...
Unit 3 (8). Data for human cases were obtained from the World Health Organization (www.who.int/csr/don/archive/country/egy/en/). From this list of cases, 1 case from period 2 was excluded because exposure to sick or dead poultry was not confirmed.

Capture-recapture methods were introduced in the field of ecology for estimating the size of wild populations and subsequently adapted to surveillance of infectious diseases in humans and animals (5,9,10). After accounting for the small sample sizes in our study (11), we used log-linear models to model cross-detection frequency data (Table 1) (12). The best model was selected by using the Akaike information criterion and projected onto the “no detection” history to estimate the frequency of districts where the virus was circulating but not reported (5). Details about our method can be found in the Online Technical Appendix (wwwnc.cdc.gov/EID/pdfs/12-0616-Techapp.pdf).

For period 1, the best model was the independent model that assumed no interaction between any of the 4 detection sources. For period 2, a significant positive interaction (p<0.05) was detected between passive surveillance and participatory surveillance. The extent of the 2 outbreaks appeared similar at district level. The actual number of districts that reported infections in poultry was estimated to be \( \approx 126 \) and 133, respectively, for period 1 and period 2 (Table 2). As a consequence, the Figure suggests that surveillance was affected heavily by underreporting during period 1. The completeness of poultry surveillance at the district level increased, rising from 46% to 69% between the 2 periods. Moreover, the sensitivity of the passive surveillance among poultry during period 2 was estimated to be more than twice as high as during period 1.

During period 2, participatory surveillance targeted zones where HPAI (H5N1) virus circulation had been informally reported in poultry, potentially overlapping spontaneous reports and resulting in a direct positive dependence on passive surveillance. No positive dependence between surveillance of humans and active or participatory surveillance of poultry was detected, even though such dependence could have been predicted because of possible investigations into poultry cases after human cases were reported.

The assumption of no indirect dependence between the 4 detection sources is the most critical aspect of this study. It is possible that all 4 sources had a higher probability of

<table>
<thead>
<tr>
<th>Detection history</th>
<th>No. districts reporting infection</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Period 1</strong></td>
<td></td>
</tr>
<tr>
<td>1 0 0 0</td>
<td>13</td>
</tr>
<tr>
<td>0 1 0 0</td>
<td>22</td>
</tr>
<tr>
<td>0 0 1 0</td>
<td>4</td>
</tr>
<tr>
<td>0 0 0 1</td>
<td>15</td>
</tr>
<tr>
<td>1 1 0 0</td>
<td>3</td>
</tr>
<tr>
<td>1 0 1 0</td>
<td>1</td>
</tr>
<tr>
<td>1 0 0 1</td>
<td>7</td>
</tr>
<tr>
<td>0 1 1 0</td>
<td>1</td>
</tr>
<tr>
<td>0 1 0 1</td>
<td>2</td>
</tr>
<tr>
<td>0 0 1 1</td>
<td>1</td>
</tr>
<tr>
<td>1 1 1 0</td>
<td>1</td>
</tr>
<tr>
<td>1 1 0 1</td>
<td>2</td>
</tr>
<tr>
<td>1 0 1 1</td>
<td>0</td>
</tr>
<tr>
<td>0 1 1 1</td>
<td>0</td>
</tr>
<tr>
<td>1 1 1 1</td>
<td>1</td>
</tr>
<tr>
<td>0 0 0 0</td>
<td>NK</td>
</tr>
</tbody>
</table>

*Columns 1–4 describe detection of infection by various protocols: 1 = infection reported using protocol; 0 = no infection reported using protocol, e.g., the first line corresponds to the districts in which infection was detected only by the active surveillance of poultry. Period 1, Dec 2008–Jun 2009; period 2, Dec 2009–Jun 2010.†Active surveillance of poultry.‡Passive surveillance of poultry.§Participatory surveillance of poultry.¶Surveillance in humans. NK, not known.
detecting districts with a high incidence of disease than a low incidence of disease. As a consequence, for each period, this positive indirect dependence is likely to result in underestimation of the true number of districts where HPAI (H5N1) virus was circulating in poultry (3), causing some districts that had few outbreaks to go uncounted. The consequence of such an underestimation is a slight overestimation of the completeness of each detection source. However, because this potential bias occurred for both periods, it should not influence the overall trend estimated between the 2 periods.

Conclusions
Our findings support the hypothesis that mass avian influenza vaccination of domestic poultry may negatively affect passive surveillance for influenza infection among poultry (4). This phenomenon could be caused by changes in the clinical features of the disease linked to vaccination (e.g., lower mortality rate, fewer clinical signs). However, these changes should be considered negligible because of the limited efficacy of this vaccination strategy in the field (4). A disproportionate trust in the benefits of AI vaccination might be a more plausible explanation. This trust could lead to failure of the community to recognize the disease, based on the assumption that poultry vaccinated against HPAI (H5N1) could no longer be infected.

This study supports an updated interpretation of the evaluation of the HPAI (H5N1) control program in Egypt. We conclude that if reported outbreaks are the only data considered, the effectiveness of AI vaccination will be overestimated. Our findings stress the critical importance of the quality of data used in the evaluation of animal and public health control programs and the necessity to evaluate reporting rates.

Acknowledgment
We thank Delphine Claybrough for reviewing the manuscript.

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References

Address for correspondence: Timothée Vergne, TA C 22/E Campus International de Baillarguet, CIRAD, 34398 Montpellier Cedex 5, France; email: timotheevergne@cirad.fr

Table 2. Estimated surveillance parameters for avian influenza virus infection in Egypt

<table>
<thead>
<tr>
<th>Estimated parameters</th>
<th>Period 1</th>
<th></th>
<th>Period 2</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Point estimates 95% CI</td>
<td>Point estimates 95% CI</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Number of districts with infection among poultry</td>
<td>126 107–159</td>
<td>133 118–160</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Completeness of the 4 detection sources</td>
<td>0.58 0.46–0.68</td>
<td>0.72 0.60–0.81</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Completeness of surveillance among poultry</td>
<td>0.46 0.36–0.54</td>
<td>0.69 0.58–0.78</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Completeness of passive surveillance</td>
<td>0.25 0.20–0.30</td>
<td>0.59 0.49–0.66</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

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Technical Appendix

Multisource Capture-Recapture Method Using Log-Linear Models (1)

For the sake of clarity, we will consider the situation where each infected epidemiologic unit can be detected by 3 detection sources, which is the simplest multisource situation. Matching these 3 detection sources allows representing the data in a detection history dataset as presented in the Table. In principle, all combinations of detection can be observed from “detected by each of the 3 sources” (7th line in Table) to “detected by none of the sources” (8th line in Table). To each detection history is associated the corresponding number of infected epidemiologic units (4th column in Table). By construction, the observed frequency of infected epidemiologic units detected by none of the 3 sources (X_{000}) is missing and needs to be estimated for getting an unbiased estimation of the true number of infected epidemiologic units.

Table. Representation of a capture history dataset with 3 detection sources

<table>
<thead>
<tr>
<th>Source 1</th>
<th>Source 2</th>
<th>Source 3</th>
<th>Frequency</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>0</td>
<td>0</td>
<td>X_{100}</td>
</tr>
<tr>
<td>0</td>
<td>1</td>
<td>0</td>
<td>X_{010}</td>
</tr>
<tr>
<td>0</td>
<td>0</td>
<td>1</td>
<td>X_{001}</td>
</tr>
<tr>
<td>1</td>
<td>1</td>
<td>0</td>
<td>X_{110}</td>
</tr>
<tr>
<td>1</td>
<td>0</td>
<td>1</td>
<td>X_{101}</td>
</tr>
<tr>
<td>0</td>
<td>1</td>
<td>1</td>
<td>X_{011}</td>
</tr>
<tr>
<td>1</td>
<td>1</td>
<td>1</td>
<td>X_{111}</td>
</tr>
<tr>
<td>0</td>
<td>0</td>
<td>0</td>
<td>X_{000}?</td>
</tr>
</tbody>
</table>

Log-linear models enable modeling the natural logarithm of observed frequencies of each capture histories as a linear combination of an intercept, detection sources main effects and, possibly, interaction terms. The presence of a structurally empty cell in the dataset prevents constructing a model that would take into account the highest-order interaction term (i.e. the 3-way interaction term in the case of 3 detection sources). The assumption of insignificance of the highest-order interaction is therefore a prerequisite for any application. For 3 detection sources,
the saturated model (taking into account all possible interactions between sources except the 3-way interaction) can be written as

\[
\begin{align*}
\ln(X_{111}) &= \theta_0 + \lambda_1 + \lambda_2 + \lambda_3 + \lambda_{12} + \lambda_{13} + \lambda_{23} \\
\ln(X_{110}) &= \theta_0 + \lambda_1 + \lambda_2 + \lambda_{12} \\
\ln(X_{101}) &= \theta_0 + \lambda_1 + \lambda_3 + \lambda_{13} \\
\ln(X_{011}) &= \theta_0 + \lambda_2 + \lambda_3 + \lambda_{23} \\
\ln(X_{100}) &= \theta_0 + \lambda_1 \\
\ln(X_{010}) &= \theta_0 + \lambda_2 \\
\ln(X_{001}) &= \theta_0 + \lambda_3
\end{align*}
\]

with \(\theta_0\) being the intercept, \(\lambda_1, \lambda_2, \lambda_3\) being the main effects of source 1, 2 and 3 respectively, \(\lambda_{12}, \lambda_{13}\) and \(\lambda_{23}\) being the interaction terms. Selecting the model presenting the best compromise between fit the data and parsimony (i.e., minimal complexity) is usually done using a backward stepwise procedure based on the Akaike information criterion.

Once the best model is selected, the estimation of \(\theta_0\) allows estimating the number of infected epidemiologic units that are not detected \((X_{000})\) with \(\widehat{X}_{000} = \exp(\widehat{\theta_0})\) and therefore estimating the total number of infected epidemiologic units \(\widehat{N}\). The estimation of the completeness of a detection source can be obtained by dividing the number of infected epidemiologic units detected by that source by the estimated total number of infected epidemiologic units.

This 3 detection sources situation corresponds to the simplest multisource case, and extension to 4 detection sources or more can be performed using the same principle.

In multisource capture-recapture applications, if there are null frequencies for some detection histories, the estimation procedures may lead to extreme or even infinite estimates. In such circumstances, Hook and Regal (1) proposed a small sample adjustment of the data: with an odd (even) number of detection sources, they suggest to add the value of 1 to the observed frequencies of the detection histories corresponding to an even (odd) number of detection sources.
**Underlying Assumptions**

In epidemiology, capture-recapture applications generally assume that a number of underlying assumptions are met. These assumptions have to be assessed for any specific case study.

The first assumption is that the sources should be directly independent: being detected by 1 source should not change the probability of being detected by another source. A positive direct dependence occurs when this probability increases which ultimately results in an underestimation of the true infected population size. With log-linear modeling, this assumption can be relaxed by using interaction terms between the dependent sources (1).

The second assumption is that the sources should be indirectly independent: if different sources experience heterogeneity in the detection probabilities (some cases are more easily detected than others) the factors driving these heterogeneities for different sources should not be correlated. A positive indirect dependence occurs when the heterogeneity factors are positively correlated, which results again in an underestimation of the true infected population size. Indirect dependencies can most often be taken into account in log-linear models with the use of interaction terms between the dependent sources. Heterogeneities in detection probabilities that are uncorrelated among sources do not hamper the application of capture-recapture (2).

The third assumption is that there are no false-positives results. The presence of false-positive results artificially inflates the observed frequencies in the detection history dataset, and generally produces overestimations.

**References**
